

CURVATURE LITE

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1 Surfaces 2 Curvature

1 Surfaces

01° Let U be a region in \mathbf{R}^2 and let H be an injective mapping carrying U to \mathbf{R}^3 . Let $S := H(U)$ be the range of H , a subset of \mathbf{R}^3 . We will refer to S as a *surface* in \mathbf{R}^3 , *parametrized* by H . We will represent members of \mathbf{R}^2 as follows:

$$u = (u^1, u^2)$$

and members of \mathbf{R}^3 as follows:

$$x = (x^1, x^2, x^3)$$

Now the mapping H can be expressed in the following form:

$$(1) \quad (u^1, u^2) = u \longrightarrow H(u) = x = (x^1(u^1, u^2), x^2(u^1, u^2), x^3(u^1, u^2))$$

We will represent the total derivative of H at u as follows:

$$DH(u) = \begin{pmatrix} H_1^1(u) & H_2^1(u) \\ H_1^2(u) & H_2^2(u) \\ H_1^3(u) & H_2^3(u) \end{pmatrix}$$

which is to say that:

$$(2) \quad H_j^a(u^1, u^2) := \frac{\partial x^a}{\partial u^j}(u^1, u^2) \quad (1 \leq j \leq 2, 1 \leq a \leq 3)$$

We require that, for each u in U , the column vectors:

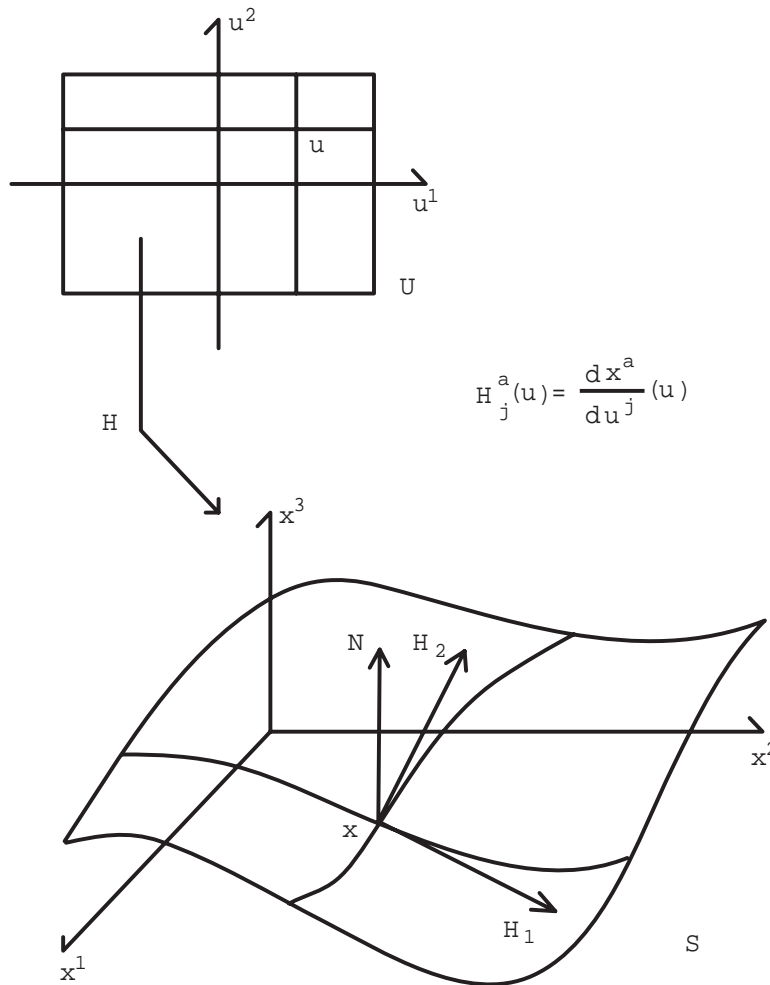
$$H_1(u) := \begin{pmatrix} H_1^1(u) \\ H_1^2(u) \\ H_1^3(u) \end{pmatrix} \quad \text{and} \quad H_2(u) := \begin{pmatrix} H_2^1(u) \\ H_2^2(u) \\ H_2^3(u) \end{pmatrix}$$

be linearly independent, which is to say that:

$$H_1(u) \times H_2(u) \neq 0$$

02° Let $N(u)$ be the unit vector normal to the surface S at the point $H(u)$:

$$(3) \quad N(u) := \frac{1}{\|H_1(u) \times H_2(u)\|} \cdot (H_1(u) \times H_2(u))$$



03° We define the *first fundamental form* G for the surface S as follows:

$$G(u) = \begin{pmatrix} G_{11}(u) & G_{12}(u) \\ G_{21}(u) & G_{22}(u) \end{pmatrix}$$

where:

$$(4) \quad G_{k\ell}(u) := H_k(u) \bullet H_\ell(u) \quad (1 \leq k \leq 2, 1 \leq \ell \leq 2)$$

One should note that $G(u)$ is a symmetric positive definite matrix.

04° We plan to describe the various metric properties of the surface S , such as the length of a curve in S , the area of a subset of S , and the curvature of S at a point. We will show that these properties can all be expressed in terms of the first fundamental form. This fact releases us from the view that, in general, a surface must lie in \mathbf{R}^3 . We may focus our attention upon the region U in \mathbf{R}^2 and the first fundamental form G :

$$G(u) = \begin{pmatrix} G_{11}(u) & G_{12}(u) \\ G_{21}(u) & G_{22}(u) \end{pmatrix}$$

with which it has in some fashion been supplied. We may then proceed to calculate the various metric properties of U in terms of G .

05° Now let J be an open interval in \mathbf{R} and let Γ be a mapping carrying J to \mathbf{R}^3 such that the range $C := \Gamma(J)$ of Γ is a subset of the surface S . We require that, for each t in J , $D\Gamma(t) \neq 0$. We shall refer to C as a *curve* in S , *parametrized* by Γ . Of course, we may introduce the mapping γ carrying J to U :

$$t \longrightarrow \gamma(t) = u = (u^1(t), u^2(t))$$

such that:

$$\begin{aligned} (\Gamma^1(t), \Gamma^2(t), \Gamma^3(t)) &= \Gamma(t) \\ &= H(\gamma(t)) \\ &= (H^1(u^1(t), u^2(t)), H^2(u^1(t), u^2(t)), H^3(u^1(t), u^2(t))) \end{aligned}$$

The mapping γ describes the given curve C in terms of the parameters u^1 and u^2 . By the Chain Rule, we have:

$$D\Gamma(t) = DH(\gamma(t))D\gamma(t)$$

Hence:

$$(5) \quad \frac{d\Gamma}{dt}(t) = \frac{du^j}{dt}(t) \cdot H_j(\gamma(t))$$

For the latter relation, we have invoked the *summation convention*, which directs that indices which appear in a given expression both “up” and “down” shall be summation indices running through their given range (in this case, from 1 to 2). In turn:

$$\left\| \frac{d\Gamma}{dt}(t) \right\|^2 = \frac{du^k}{dt}(t) G_{k\ell}(u^1(t), u^2(t)) \frac{du^\ell}{dt}(t)$$

Now we may proceed to calculate the *length* of the segment of the curve C in S from $\Gamma(t')$ to $\Gamma(t'')$:

$$(6) \quad \int_{t'}^{t''} \|D\Gamma(t)\| dt = \int_{t'}^{t''} \sqrt{\frac{du^k}{dt}(t) G_{k\ell}(u^1(t), u^2(t)) \frac{du^\ell}{dt}(t)} dt$$

where t' and t'' are any numbers in J for which $t' \leq t''$. We are led to interpret:

$$(7) \quad \|V\| := \sqrt{V^k G_{k\ell}(u) V^\ell}$$

as the *length* of the tangent vector:

$$V := \begin{pmatrix} V^1 \\ V^2 \end{pmatrix}$$

to U at u , and to interpret:

$$\int_{t'}^{t''} \sqrt{\frac{du^k}{dt}(t) G_{k\ell}(u^1(t), u^2(t)) \frac{du^\ell}{dt}(t)} dt$$

as the *length* of the segment of the curve γ in U from $\gamma(t')$ to $\gamma(t'')$. More generally, we interpret:

$$(8) \quad V \circ W := V^k G_{k\ell}(u) W^\ell$$

as the *inner product* of the vectors:

$$V = \begin{pmatrix} V^1 \\ V^2 \end{pmatrix} \quad \text{and} \quad W = \begin{pmatrix} W^1 \\ W^2 \end{pmatrix}$$

in \mathbf{R}^2 , tangent to U at u .

06° We may also proceed to calculate the *area* of a subset T of S , as follows. We first present T as $T = H(V)$, where V is a subset of U . We then equate the *area* of T with the following double integral:

$$(9) \quad \text{area}(T) := \int \int_V \|H_1(u^1, u^2) \times H_2(u^1, u^2)\| du^1 du^2$$

Since:

$$\|H_1(u) \times H_2(u)\|^2 = G_{11}(u)G_{22}(u) - G_{21}(u)G_{12}(u) =: g(u)$$

we interpret:

$$(10) \quad \text{area}(V) := \int \int_V \sqrt{g(u^1, u^2)} du^1 du^2$$

as the area of the subset V of U .

2 Curvature

07° Let us consider a particular point \bar{P} :

$$\bar{P} = (\bar{x}^1, \bar{x}^2, \bar{x}^3) = H(\bar{u}^1, \bar{u}^2)$$

in the surface S . We plan to describe the *curvature* of S at \bar{P} . To that end, let us consider a curve C in S containing \bar{P} . The curvature of C at \bar{P} derives in part from the bending of C within S and in part from the bending of S itself. One may refer to the former as the *internal* bending of C and to the latter as the *external* bending. One may say that the internal bending is a matter of free choice but that the external bending is forced upon the curve by the structure of the surface. Among all curves C in S containing \bar{P} , we may consider those for which the external bending is minimum and those for which it is maximum. By definition, the *gaussian curvature* of the surface S at the point \bar{P} is the product of these two extreme values.

08° Let J be an open interval in \mathbf{R} and let Γ be a mapping carrying J to \mathbf{R}^3 such that $C := \Gamma(J)$. As usual, we require that, for each t in J , $D\Gamma(t) \neq 0$. For convenience, let 0 be in J and let $\Gamma(0) = \bar{P}$. In turn, let γ be the mapping carrying J to U :

$$t \longrightarrow \gamma(t) = u = (u^1(t), u^2(t))$$

such that:

$$\begin{aligned} (\Gamma^1(t), \Gamma^2(t), \Gamma^3(t)) &= \Gamma(t) \\ &= H(\gamma(t)) \\ &= (H^1(u^1(t), u^2(t)), H^2(u^1(t), u^2(t)), H^3(u^1(t), u^2(t))) \end{aligned}$$

Of course, $\gamma(0) = \bar{u} = (\bar{u}^1, \bar{u}^2)$. We have:

$$\frac{d\Gamma}{dt}(t) = \frac{du^j}{dt}(t) \cdot H_j(\gamma(t))$$

and:

$$\frac{d^2\Gamma}{dt^2}(t) = \frac{d^2u^j}{dt^2}(t) \cdot H_j(\gamma(t)) + \frac{du^k}{dt}(t) \frac{du^\ell}{dt}(t) \cdot H_{k\ell}(\gamma(t))$$

where:

$$(11) \quad H_{k\ell}(u) := \frac{\partial^2 H}{\partial u^k \partial u^\ell}(u)$$

Now we may introduce functions $K_{k\ell}^j$ and $L_{k\ell}$ such that:

$$(12) \quad H_{k\ell}(u) = K_{k\ell}^j(u) \cdot H_j(u) + L_{k\ell}(u) \cdot N(u)$$

The foregoing relations are called *Gauss' Equations*. One should note carefully that:

$$(13) \quad L_{k\ell}(u) = H_{k\ell}(u) \bullet N(u)$$

One refers to L :

$$L(u) = \begin{pmatrix} L_{11}(u) & L_{12}(u) \\ L_{21}(u) & L_{22}(u) \end{pmatrix}$$

as the *second fundamental form* for the surface S . One refers to K^1 and K^2 :

$$K^1(u) = \begin{pmatrix} K_{11}^1(u) & K_{12}^1(u) \\ K_{21}^1(u) & K_{22}^1(u) \end{pmatrix} \quad \text{and} \quad K^2(u) = \begin{pmatrix} K_{11}^2(u) & K_{12}^2(u) \\ K_{21}^2(u) & K_{22}^2(u) \end{pmatrix}$$

as the *connection coefficients* for S . Finally, we obtain:

$$(14) \quad \frac{d^2\Gamma}{dt^2}(t) = A^j(t) \cdot H_j(\gamma(t)) + B(t) \cdot N(\gamma(t))$$

where:

$$(15) \quad A^j(t) := \frac{d^2u^j}{dt^2}(t) + \frac{du^k}{dt} K_{k\ell}^j(\gamma(t))(t) \frac{du^\ell}{dt}(t)$$

and:

$$(16) \quad B(t) := \frac{du^k}{dt}(t) L_{k\ell}(\gamma(t)) \frac{du^\ell}{dt}(t)$$

Clearly:

$$A^j(t) \cdot H_j(\gamma(t))$$

is tangent to S at $H(u)$. It represents the internal bending of C at $H(u)$.
Moreover:

$$B(t) \cdot N(\gamma(t))$$

is normal to S at $H(u)$. It represents the external bending of C at $H(u)$.

09° At this point, we are interested in the value of $B(0)$:

$$(17) \quad B(0) = \frac{du^k}{dt}(0)L_{k\ell}(\bar{u})\frac{du^\ell}{dt}(0)$$

since it measures the “external bending” of C at \bar{P} . To set the scale of computation, we require that C be parametrized by arc length. The effect of this requirement is to force:

$$\frac{du^k}{dt}(t)G_{k\ell}(\gamma(t))\frac{du^\ell}{dt}(t) = 1$$

In particular:

$$(18) \quad \frac{du^k}{dt}(0)G_{k\ell}(\bar{u})\frac{du^\ell}{dt}(0) = 1$$

Now we wish to study the minimum and maximum values of the quantity:

$$V^k L_{k\ell}(\bar{u})V^\ell$$

where V is any vector in \mathbf{R}^2 meeting the condition:

$$V^k G_{k\ell}(\bar{u})V^\ell = 1$$

The product of these extreme values is the gaussian curvature for S at \bar{P} .

10° Here is our problem. We have two symmetric matrices:

$$L = \begin{pmatrix} L_{11} & L_{12} \\ L_{21} & L_{22} \end{pmatrix}$$

and:

$$G = \begin{pmatrix} G_{11} & G_{12} \\ G_{21} & G_{22} \end{pmatrix}$$

The latter is positive definite. These matrices define functions (“quadratic forms”) as follows:

$$\lambda(V) := V^k L_{k\ell}V^\ell = (V^1 \quad V^2) \begin{pmatrix} L_{11} & L_{12} \\ L_{21} & L_{22} \end{pmatrix} \begin{pmatrix} V^1 \\ V^2 \end{pmatrix}$$

and:

$$\gamma(V) := V^k G_{k\ell}V^\ell = (V^1 \quad V^2) \begin{pmatrix} G_{11} & G_{12} \\ G_{21} & G_{22} \end{pmatrix} \begin{pmatrix} V^1 \\ V^2 \end{pmatrix}$$

We wish to calculate the product of the minimum and the maximum values of the quantity $\lambda(V)$, subject to the condition $\gamma(V) = 1$. By “diagonalizing” the quadratic form L relative to the (positive definite) quadratic form G , one can show that the foregoing product equals:

$$\frac{L_{11}L_{22} - L_{21}L_{12}}{G_{11}G_{22} - G_{21}G_{12}}$$

Accordingly, we define the curvature of the surface S at the point \bar{P} to be:

$$(19) \quad \begin{aligned} \kappa_S(\bar{P}) &:= \frac{L_{11}(\bar{u})L_{22}(\bar{u}) - L_{21}(\bar{u})L_{12}(\bar{u})}{G_{11}(\bar{u})G_{22}(\bar{u}) - G_{21}(\bar{u})G_{12}(\bar{u})} \\ &= \frac{L_{11}(\bar{u})L_{22}(\bar{u}) - L_{21}(\bar{u})L_{12}(\bar{u})}{g(\bar{u})} \end{aligned}$$