

DYNAMICAL SYSTEMS / RANDOM PROCESSES

Thomas Wieting
Reed College, 2006

1° Let X be a set, let \mathcal{A} be a borel algebra of subsets of X , and let μ be a normalized measure defined on \mathcal{A} . One refers to the ordered triple:

$$(X, \mathcal{A}, \mu)$$

as a (*normalized*) *measure space*, but sometimes as a *probability space*. Let T be a borel mapping carrying X to itself for which μ is *invariant*:

$$T_*(\mu) = \mu$$

One refers to the ordered quadruple:

$$(X, \mathcal{A}, \mu, T)$$

as an (*abstract*) *dynamical system*.

2° Now let:

$$(X, \mathcal{A}, \mu)$$

be a probability space and let:

$$f_0, f_1, f_2, \dots, f_j, \dots$$

be a sequence of (real-valued) borel functions defined on X . One may just as well present the foregoing sequence as a (borel) mapping F carrying X to $\mathbf{R}^{\mathbf{N}}$, defined as follows:

$$F(x) := (f_0(x), f_1(x), f_2(x), \dots, f_j(x), \dots) \quad (x \in X)$$

Obviously, one may recover the sequence:

$$f_0, f_1, f_2, \dots, f_j, \dots$$

from the mapping F by applying the projections:

$$p_j(t) := t_j \quad (t = (t_0, t_1, t_2, \dots, t_j, \dots) \in \mathbf{R}^{\mathbf{N}})$$

carrying $\mathbf{R}^{\mathbf{N}}$ to \mathbf{R} . Thus:

$$f_j = p_j \cdot F \quad (j \in \mathbf{N})$$

One refers to the ordered quadruple:

$$(X, \mathcal{A}, \mu, F)$$

as a *random process*. The various borel functions in the sequence:

$$f_0, f_1, f_2, \dots, f_j, \dots$$

are the *random variables* comprising the random process. For each nonnegative integer j , one defines the *marginal distribution* for f_j as follows:

$$\nu_j := (f_j)_*(\mu)$$

Of course:

$$\nu_j$$

is a normalized measure on \mathbf{R} . One says that the random process is *identically distributed (id)* iff all the marginal distributions coincide:

$$\nu_j := \nu_0 \quad (j \in \mathbf{N})$$

For any finite strictly increasing sequence:

$$j_1 < j_2 < j_3 < \dots < j_n$$

of nonnegative integers, one defines the *joint marginal distribution* as follows:

$$\nu_{j_1 j_2 \dots j_n} := (f_{j_1} \times f_{j_2} \times \dots \times f_{j_n})_*(\mu)$$

Of course:

$$\nu_{j_1 j_2 \dots j_n}$$

is a normalized measure on (the borel algebra comprised of the borel subsets of) \mathbf{R}^n . One says that the random process is *stationary* iff, for any finite strictly increasing sequence:

$$j_1 < j_2 < j_3 < \dots < j_n$$

of nonnegative integers and for any positive integer k :

$$\nu_{j_1 j_2 \dots j_n} = \nu_{k_1 k_2 \dots k_n}$$

where:

$$k_1 := j_1 + k, \quad k_2 := j_2 + k, \quad \dots, \quad k_n := j_n + k$$

In due course, we will reformulate this formidably abstract condition in more comprehensible “geometric” terms. Taking n to be 1, one can readily check that if the random process is stationary then it is identically distributed.

One says that the random process is *independent* iff, for any finite strictly increasing sequence:

$$j_1 < j_2 < j_3 < \cdots < j_n$$

of nonnegative integers:

$$\nu_{j_1, j_2, \dots, j_n} = \prod_{m=1}^n \nu_{j_m}$$

One can readily check that if the random process is independent and identically distributed (*iid*) then it is stationary. One sometimes refers to an iid random process as a *bernoulli* process.

3° Let:

$$(X, \mathcal{A}, \mu, T)$$

be a dynamical system and let:

$$h$$

be a (real-valued) borel function defined on X . One defines the corresponding random process:

$$(X, \mathcal{A}, \mu, F)$$

as follows:

$$(1) \quad f_j := h \cdot T^j$$

Clearly:

$$F(x) = (h(T^0(x)), h(T^1(x)), h(T^2(x)), \dots, h(T^j(x)), \dots) \quad (x \in X)$$

We may say that the ordered quintuple:

$$(X, \mathcal{A}, \mu, T, h)$$

comprised of the dynamical system:

$$(X, \mathcal{A}, \mu, T)$$

and the *observable*:

$$h$$

defines the corresponding random process:

$$(X, \mathcal{A}, \mu, F)$$

by means of relation (1). One can readily show that this random process is stationary.

4° Conversely, let:

$$(X, \mathcal{A}, \mu, F)$$

be a random process. Let:

$$\nu$$

be the (normalized) measure defined on (the borel algebra \mathcal{B} comprised of the borel subsets of) $\mathbf{R}^{\mathbf{N}}$ as follows:

$$(2) \quad \nu := F_*(\mu)$$

Let Σ be the (borel) mapping carrying $\mathbf{R}^{\mathbf{N}}$ to itself, defined as follows:

$$(3) \quad \begin{aligned} \Sigma(t) &:= u \\ &= (u_0, u_1, u_2, \dots, u_j, \dots) \quad (t = (t_0, t_1, t_2, \dots, t_j, \dots) \in \mathbf{R}^{\mathbf{N}}) \\ &:= (t_1, t_2, t_3, \dots, t_{j+1}, \dots) \end{aligned}$$

One can readily show that if the given random process is stationary then ν is invariant for Σ :

$$\Sigma_*(\nu) = \nu$$

In fact, the relation just stated provides a natural, rather more intuitive view of the condition that the given random process be stationary. We may say that the random process:

$$(X, \mathcal{A}, \mu, F)$$

if stationary, defines the dynamical system:

$$(\mathbf{R}^{\mathbf{N}}, \mathcal{B}, \nu, \Sigma)$$

by means of relations (2) and (3). The observable:

$$p_0$$

completes the picture:

$$(\mathbf{R}^{\mathbf{N}}, \mathcal{B}, \nu, \Sigma, p_0)$$

5° We may summarize the foregoing transitions in the following schematic form:

$$(X, \mathcal{A}, \mu, T, h) \longrightarrow (X, \mathcal{A}, \mu, F) \longrightarrow (\mathbf{R}^{\mathbf{N}}, \mathcal{B}, \nu, \Sigma, p_0)$$

One should note that:

$$(X, \mathcal{A}, \mu, T, h)$$

and:

$$(\mathbf{R}^{\mathbf{N}}, \mathcal{B}, \nu, \Sigma, p_0)$$

are closely related, in that the borel mapping F carries X to $\mathbf{R}^{\mathbf{N}}$:

$$F : X \longrightarrow \mathbf{R}^{\mathbf{N}}$$

F transforms μ to ν :

$$F_*(\mu) = \nu$$

F intertwines T and Σ :

$$\Sigma \cdot F = F \cdot T$$

and F transforms p_0 to h :

$$h = p_0 \cdot F$$

6° One may continue the process one more time. The dynamical system:

$$(\mathbf{R}^{\mathbf{N}}, \mathcal{B}, \nu, \Sigma)$$

and the observable:

$$p_0$$

define the random process:

$$(\mathbf{R}^{\mathbf{N}}, \mathcal{B}, \nu, I)$$

where I is the identity mapping carrying $\mathbf{R}^{\mathbf{N}}$ to itself. The corresponding sequence of random variables for this random process is the sequence of projections:

$$p_0, p_1, p_2, \dots, p_j, \dots$$

The relevant point is that:

$$p_j = p_0 \cdot \Sigma_j \quad (j \in \mathbf{N})$$

One should note that:

$$(X, \mathcal{A}, \mu, F)$$

and:

$$(\mathbf{R}^{\mathbf{N}}, \mathcal{B}, \nu, I)$$

are closely related, in that the borel mapping F carries X to $\mathbf{R}^{\mathbf{N}}$:

$$F : X \longrightarrow \mathbf{R}^{\mathbf{N}}$$

F transforms μ to ν :

$$F_*(\mu) = \nu$$

and F transforms the sequence:

$$p_0, p_1, p_2, \dots, p_j, \dots$$

to the sequence:

$$f_0, f_1, f_2, \dots, f_j, \dots$$

which is to say that:

$$f_j = p_j \cdot F \quad (j \in \mathbf{N})$$