

MATHEMATICS 322
DIVERGENCE

Field and Flow

01° Let F be a vector field defined on \mathbf{R}^3 :

$$F(x, y, z) = (A(x, y, z), B(x, y, z), C(x, y, z))$$

Let Γ be the corresponding flow, defined by the Existence/Uniqueness Theorem for Ordinary Differential Equations:

$$\Gamma(t, x, y, z) = (U(t, x, y, z), V(t, x, y, z), W(t, x, y, z))$$

By definition:

$$\Gamma_t(t, x, y, z) = F(\Gamma(t, x, y, z))$$

Moreover:

$$\Gamma(0, x, y, z) = (x, y, z)$$

Hence:

$$U(0, x, y, z) = x, \quad V(0, x, y, z) = y, \quad W(0, x, y, z) = z$$

Notation

02° We adopt the following notation:

$$\Gamma(t)(x, y, z) = \Gamma(t, x, y, z) = \Gamma(x, y, z)(t)$$

so that we may view $\Gamma(x, y, z)$ as the integral curve for F passing through (x, y, z) at $t = 0$ and we may view $\Gamma(t)$ as a mapping carrying \mathbf{R}^3 to itself. Naturally, we may apply similar notational refinements to the functions U , V , and W .

03° By the Uniqueness Theorem, we find that, for any s and t :

$$\Gamma(s + t) = \Gamma(s) \cdot \Gamma(t)$$

Transformation of Volume

04° Now let V be a closed bounded region in \mathbf{R}^3 and let $V(t)$ be the image of V under $\Gamma(t)$:

$$V(t) = \Gamma(t)(V)$$

Let $\lambda(V(t))$ stand for the volume of $V(t)$. We plan to compute:

$$\frac{d}{dt}\lambda(V(t))$$

By the basic relation for the transformation of integrals, we have:

$$\begin{aligned}\lambda(V(t)) &= \iiint_{V(t)} 1 \cdot dx dy dz \\ &= \iiint_V \det D\Gamma(t)(u, v, w) \cdot dudvdw\end{aligned}$$

We contend that:

$$(\Delta) \quad \frac{d}{dt}\lambda(V(t)) = \iiint_{V(t)} (\operatorname{div} F)(x, y, z) \cdot dx dy dz$$

One may rightly refer to the foregoing relation as the Divergence Theorem.

05° For the proof of relation (Δ) , we introduce the matrix:

$$M(t, u, v, w) = D\Gamma(t)(u, v, w)$$

and we invoke our prior notational conventions. We find that:

$$\begin{aligned}\frac{\partial}{\partial t}M(t, u, v, w) &= \frac{\partial}{\partial t}D\Gamma(t)(u, v, w) \\ &= \begin{pmatrix} U_{tu}(t, u, v, w) & U_{tv}(t, u, v, w) & U_{tw}(t, u, v, w) \\ V_{tu}(t, u, v, w) & V_{tv}(t, u, v, w) & V_{tw}(t, u, v, w) \\ W_{tu}(t, u, v, w) & W_{tv}(t, u, v, w) & W_{tw}(t, u, v, w) \end{pmatrix} \\ &= \begin{pmatrix} U_{ut}(t, u, v, w) & U_{vt}(t, u, v, w) & U_{wt}(t, u, v, w) \\ V_{ut}(t, u, v, w) & V_{vt}(t, u, v, w) & V_{wt}(t, u, v, w) \\ W_{ut}(t, u, v, w) & W_{vt}(t, u, v, w) & W_{wt}(t, u, v, w) \end{pmatrix} \\ &= D \frac{\partial}{\partial t}\Gamma(u, v, w)(t) \\ &= DF(\Gamma(u, v, w)(t)) \\ &= DF(\Gamma(t)(u, v, w)) \\ &= D(F \cdot \Gamma(t))(u, v, w) \\ &= DF(\Gamma(t)(u, v, w))D\Gamma(t)(u, v, w) \\ &= A(t, u, v, w)M(t, u, v, w)\end{aligned}$$

where:

$$A(t, u, v, w) = DF(\Gamma(t)(u, v, w))$$

By common knowledge:

$$(\bullet) \quad \det M(t, u, v, w) = \exp\left(\int_0^t \operatorname{tr} A(s, u, v, w) ds\right) \det M(0, u, v, w)$$

while, in our case:

$$\det M(0, u, v, w) = 1$$

Hence:

$$\begin{aligned} & \frac{d}{dt} \lambda(V(t)) \\ &= \iiint_V \frac{\partial}{\partial t} \det D\Gamma(t)(u, v, w) \cdot dudvdw \\ &= \iiint_V \frac{\partial}{\partial t} \exp\left(\int_0^t \operatorname{tr}(DF(\Gamma(s)(u, v, w)) ds\right) \cdot dudvdw \\ &= \iiint_V \exp\left(\int_0^t \operatorname{tr}(DF(\Gamma(s)(u, v, w)) ds\right) \operatorname{tr}(DF(\Gamma(t)(u, v, w)) \cdot dudvdw \\ &= \iiint_V \det D\Gamma(t)(u, v, w) \operatorname{tr}(DF(\Gamma(t)(u, v, w)) \cdot dudvdw \\ &= \iiint_V (\operatorname{div} F)(\Gamma(t)(u, v, w)) \det D\Gamma(t)(u, v, w) \cdot dudvdw \\ &= \iiint_{V(t)} (\operatorname{div} F)(x, y, z) \cdot dx dy dz \end{aligned}$$

06° Let us defend relation (\bullet) . To that end, we simplify the notation:

$$(*) \quad \frac{d}{dt} M(t) = A(t)M(t)$$

In turn, we introduce the standard basis for \mathbf{R}^3 :

$$E_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad E_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad E_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix},$$

Obviously:

$$\det M(t) = \det (M(t)E_1 \quad M(t)E_2 \quad M(t)E_3)$$

By relation $(*)$, we find that:

$$\frac{d}{dt} \det M(t) = \operatorname{tr} A(t) \det M(t)$$

Now relation (•) follows by application of the simplest of results in the theory of first order linear Ordinary Differential Equations.

The Lorenz Field

07° As a prime example, we introduce the following vector field, specifically, the Lorenz field:

$$L(x, y, z) = (-\sigma x + \sigma y, rx - y - xz, -bz + xy)$$

where $\sigma = 10$, $b = 8/3$ and $r = 28$. Straightway, we note that:

$$(\operatorname{div} L)(x, y, z) = -\sigma - 1 - b = -41/3$$

In turn, we find that:

$$\frac{d}{dt}\lambda(V(t)) = -\rho\lambda(V(t)) \quad (\rho = \sigma + 1 + b)$$

Consequently:

$$\lambda(V(t)) = e^{-\rho t}\lambda(V(0))$$

We infer that:

$$\lambda(\Sigma) = 0$$

where Σ is the Future Limit Set, that is, the Attractor, for L :

$$\Sigma = \bigcap_{0 \leq s} \operatorname{clo} \left(\bigcup_{s \leq t} \Gamma(t)(E) \right)$$

and where E is a carefully designed ellipsoid such that:

(•) E is *future absorbing*, which is to say that, for each (x, y, z) in \mathbf{R}^3 , there exists t in \mathbf{R} such that $0 \leq t$ and such that $\Gamma(t)(x, y, z)$ lies in E

(•) E is *future invariant*, which is to say that, for each (x, y, z) in E and for any t in \mathbf{R} , if $0 \leq t$ then $\Gamma(t)(x, y, z)$ lies in E